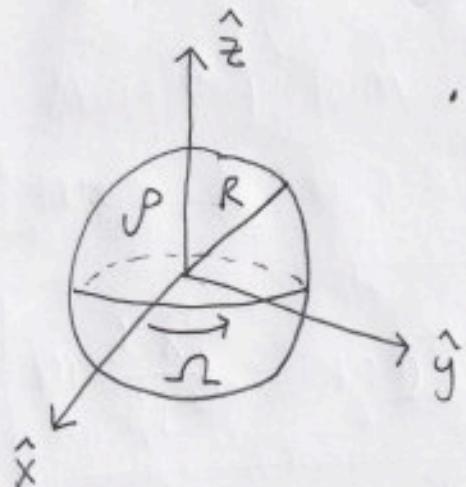


Gravitomagnetism

- In lecture we examined the linearized EFE in the Lorentz / Harmonic Gauge:
- $\square \bar{h}_{\mu\nu} = -16\pi G T_{\mu\nu} \rightarrow \nabla^2 \bar{h}_{\mu\nu} = -16\pi G T_{\mu\nu}$   
for a static source
- Now imagine the source slowly rotates and is characterized by spin spatial components  $s^i$  as well as mass  $M$ .

- a. Consider the source to be a sphere of radius  $R$  & density  $\rho$  rotating about  $\hat{z}$  with angular velocity  $\Omega$ . Find  $T_{\mu\nu}$  to 1st order in  $\Omega$ :



- Assume the sphere is a collection of dust and  $\gamma \approx dt/d\tau \approx 1$

$$\Rightarrow T_{\mu\nu} = \rho u_\mu u_\nu$$

where  $\vec{u} \approx (1, d\vec{x}/d\tau)$

- for ccw rotation,  $v_x = -\Omega y$  and  
 $v_y = \Omega x$  and  $v_z = 0 \dots$

$$\rightarrow \vec{u} = (1, -\nu y, \nu x, 0)$$

$$\rightarrow [T_{\nu r}] = P \begin{bmatrix} 1 & -\nu y & \nu x & 0 \\ -\nu y & O(\nu^2) & O(\nu^2) & 0 \\ \nu x & O(\nu^2) & O(\nu^2) & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

• Let  
 $O(\nu^2) \rightarrow 0$

• where  $x = r \sin \theta \cos \varphi$ , and  $y = r \sin \theta \sin \varphi$

b • solve for the Cartesian off-diagonal components

~~h<sub>ox</sub>, h<sub>oy</sub>, h<sub>oz</sub>~~ where  $\bar{h}_{oi} = h_{oi}$  trace reversal has no effect on off-diagonal components.

• Use the fact that:

$$h_{oi}(\vec{x}) = 4G \int \frac{T_{oi}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x'$$

$$\frac{1}{|\vec{x} - \vec{x}'|} = \frac{1}{r} + \frac{x^j x'^j}{r^3} + \dots$$

• Start with  $h_{ox}$  

$$h_{ox} = 4G \int_{V^3} \left( \frac{1}{r} + \frac{xx' + yy' + zz'}{r^3} \right) (-\nabla y' \rho) d^3x'$$

• Convert to spherical coords:

$$= -4G \nabla \rho \int_{V^3} \left( \frac{1}{r} + \frac{rr'}{r^3} (\sin \theta \sin \theta' \cos \varphi \cos \varphi' + \sin \theta \sin \theta' \sin \varphi \sin \varphi' + \cos \theta \cos \theta') \right) (r' \sin \theta' \sin \varphi') r'^2 \sin \theta' dr' d\theta' d\varphi'$$

where  $\int_{V^3} \rightarrow \int_0^R dr' \int_0^\pi d\theta' \int_0^{2\pi} d\varphi'$

• The 1st part of the integrand with  $\frac{1}{r}$  goes to zero

since  $\int_0^{2\pi} d\varphi' \sin \varphi' = -\cos \varphi' \Big|_0^{2\pi} = 0$

$$\begin{aligned} \rightarrow h_{ox} &= -\frac{4G \nabla \rho R^5}{5r^2} \int_0^{2\pi} d\varphi' \int_0^\pi d\theta' \left[ \sin^3 \theta' \sin \varphi' \cos \varphi' \sin \theta \cos \varphi' \right. \\ &\quad \left. + \sin^3 \theta' \sin^2 \varphi' \sin \theta \sin \varphi' + \sin^2 \theta' \cos \theta' \cos \theta \right] \end{aligned}$$

$$\int_0^{2\pi} d\varphi' \sin \varphi' \cos \varphi' = 0 \quad ; \quad \int_0^\pi d\theta' \cos \theta' = 0$$

$$\rightarrow h_{ox} = \frac{-4G\eta \rho R^5}{5r^2} \left( \int_0^{2\pi} d\varphi' \int_0^\pi d\theta' \sin^3 \theta' \sin^2 \varphi' \sin \theta \sin \varphi \right)$$

$$\int_0^{2\pi} d\varphi' \sin^2 \varphi' = \left[ \frac{\varphi'}{2} - \sin(2\varphi')/4 \right] \Big|_0^{2\pi} = \pi$$

$$\int_0^\pi d\theta' \sin^3 \theta' = \left[ -\cos(\theta') + \frac{\cos^3(\theta')}{3} \right] \Big|_0^\pi$$

$$= 1 - \frac{1}{3} + 1 - \frac{1}{3} = \frac{4}{3}$$

$$\rightarrow h_{ox} = \frac{-16\pi G \eta \rho R^5}{15r^2} \sin \theta \sin \varphi$$

• Multiply top + bottom by "r" + plug in  $y = r \sin \theta \sin \varphi$  to yield:

$$h_{ox} = \frac{-16\pi G \eta \rho R^5 y}{15r^3} \propto -\frac{\rho R^5 y}{r^3}$$

• More tedious integrals + the fact that  $T_{oz} = 0$  yield similarly that:

$$h_{oy} = \frac{16\pi G \eta \rho R^5 x}{15r^3} \propto \frac{\rho R^5 x}{r^3} \quad \text{and} \quad h_{oz} = 0$$

C. Using the identity  $S^i = I \boldsymbol{\tau}^i$  where  $I$  is the moment of inertia rewrite your answer in terms of  $S^i$ :

$$S^z = I \boldsymbol{\tau}^z = I \boldsymbol{\tau}, \boldsymbol{\tau}^x = \boldsymbol{\tau}^y = 0$$

$$I_{\text{sphere}} = \frac{2}{5} M R^2$$

$$= \frac{2}{5} \left( \frac{4\pi R^3}{3} \rho \right) R^2 = \frac{8\pi \rho R^5}{15}$$

$$\rightarrow h_{ox} = \frac{-16\pi 6 \rho R^5}{15r^3} \cdot y \cdot \frac{15S^2}{8\pi \rho R^5} = -\frac{2GS^2y}{r^3}$$

$$\rightarrow h_{ox} = -\frac{2GyS^2}{r^3}$$

similarly;

$$h_{oy} = \frac{2GxS^2}{r^3}$$

$$h_{oz} = 0$$

• Convert to spherical coordinates and find  $h_{or}$ ,  $h_{o\theta}$ ,  ~~$h_{o\phi}$~~   $h_{o\phi}$ :

Define  $\vec{h}_o = [h_{ox}, h_{oy}, h_{oz}]$

$$\rightarrow \vec{h}_o = \frac{2GS^2}{r^3} [-y, x, 0]$$

$$\rightarrow \vec{h}_o = \frac{2GS^2}{r^3} \cdot r [-\sin\theta \sin\varphi, \sin\theta \cos\varphi, 0]$$

$$\rightarrow \vec{h}_o = \frac{2GS^2 \sin\theta}{r^2} [-\sin\varphi, \cos\varphi, 0]$$

• According to Wikipedia, in an orthonormal basis:

$$\hat{\phi} = [-\sin\varphi, \cos\varphi, 0]$$

$$\hat{r} = [\sin\theta \cos\varphi, \sin\theta \sin\varphi, \cos\theta]$$

$$\hat{\theta} = [\cos\theta \cos\varphi, \cos\theta \sin\varphi, -\sin\theta]$$

• We want to work in a coordinate basis in which case we would append / multiply each of these unit vectors by  $\sqrt{g_{\theta\theta}}$ ,  $\sqrt{g_{rr}}$ , and  $\sqrt{g_{\theta\theta}}$  respectively.

• We can find  $h_{o\theta}$ ,  $h_{o\varphi}$ ,  $h_{or}$  via:

$$h_{o\theta} = \vec{h}_o \cdot \sqrt{g_{\theta\theta}} \hat{\theta}$$

$$h_{o\varphi} = \vec{h}_o \cdot \sqrt{g_{\varphi\varphi}} \hat{\varphi}$$

$$h_{or} = \vec{h}_o \cdot \sqrt{g_{rr}} \hat{r}$$

doing so we  
find that:



$$h_{\theta\theta} = h_{\theta r} = 0$$

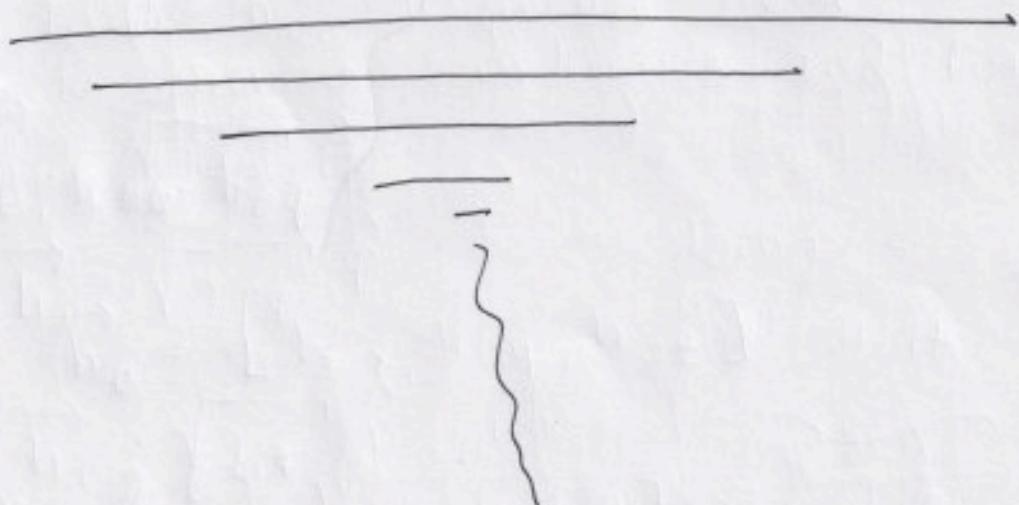
$$h_{\varphi\varphi} = \frac{2 G S^2 \sin^2 \theta}{r^2} \cdot \sqrt{g_{\varphi\varphi}} \left( \underbrace{\sin^2 \varphi + \cos^2 \varphi}_{+1} \right)$$
$$\sqrt{r^2 \sin^2 \theta}$$

$$\rightarrow h_{\varphi\varphi} = \frac{2 G S^2 \sin^2 \theta}{r}$$

$$h_{\theta\theta} = h_{\theta r} = 0$$

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- 2 Comparison of linearized GR + Maxwell Theory  
 • consider the line element:

$$ds^2 = -(1+2\phi)dt^2 + (1-2\phi)(dx^2 + dy^2 + dz^2) - 2\beta^i dx^i dt$$

i.e. the usual weak field line element with  
 $h^{00} = -\beta^i \beta_i$ .

- a Show that the geodesic equation for a particle moving in this spacetime gives the following EOM:

$$m \frac{d^2 \vec{x}}{d\tau^2} = m \vec{g} + m(\vec{v} \times \vec{H})$$

where  $\vec{g} = -\bar{\nabla}\phi$  and  $\vec{H} = \bar{\nabla} \times \vec{\beta}$

- First use the non-relativistic approximation  
 $\vec{u} = (1, \vec{v})$ . Now write out the geodesic equation:

$$\frac{d^2 x^\lambda}{d\tau^2} = - \Gamma_{\nu\nu}^\lambda u^\nu u^\nu$$

- Consider only spatial indices  $\lambda \rightarrow i$  and plug in definition of  $\vec{u}$ :

$$\Rightarrow \frac{d^2 x^i}{d\tau^2} = - \Gamma_{tt}^i u^t u^t - \Gamma_{ij}^i v^i v^j \xrightarrow{O(v^2) \rightarrow 0}$$

$$- \Gamma_{ti}^j u^t v^i - \Gamma_{jt}^i v^j u^t$$

$$\Rightarrow \frac{d^2 X^i}{d t^2} = -\Gamma_{tt}^i - 2\Gamma_{tj}^i v^j$$

• Calculate  $\Gamma_{tt}^i$  and  $\Gamma_{tj}^i$  using the fact that  
in linearized GR:

$$\Gamma_{\alpha\beta}^\nu = \frac{1}{2} n^{\nu r} (\partial_\alpha h_{\beta r} + \partial_\beta h_{\alpha r} - \partial_r h_{\alpha\beta})$$

(see e.g. Tapir's notes online...)

• In our case  $g_{\nu r} = n_{\nu r} + h_{\nu r}$  where

$$h_{00} = -2\phi, h_{0i} = -\beta_i, h_{ij} = -2\phi, h_{io} = -\beta_i$$

$$\rightarrow \Gamma_{tt}^i = \left(\frac{1}{2} n^{ir}\right) (\partial_t h_{tr} + \partial_t h_{ir} - \partial_r h_{tt})$$

$\downarrow \quad \downarrow$  since stationary  $\Rightarrow \partial_t \rightarrow 0$

$$\begin{aligned} \rightarrow \Gamma_{tt}^i &= -\frac{1}{2} n^{ii} \partial_i h_{tt} \\ &= -\frac{1}{2} n^{ii} (-2\partial_i \phi) = n^{ii} \partial_i \phi \end{aligned}$$

$$\bullet \text{Now find } \Gamma_{tj}^i = \left(\frac{1}{2} n^{ir}\right) (\partial_t h_{jr} + \partial_j h_{tr} - \partial_r h_{tj})$$

$\downarrow \quad \downarrow$

$$\rightarrow \Gamma_{tj}^i = \left(\frac{1}{2} n^{ir}\right) \left( \partial_j h_{tr} - \partial_r h_{tj} \right)$$

$$= \frac{1}{2} n^{ii} \partial_j h_{ti} - \frac{1}{2} n^{ii} \partial_i h_{tj} \text{ since } n \text{ diagonal...}$$

$$= \left(\frac{1}{2} n^{ii}\right) \left( \partial_j \beta_i - \partial_i \beta_j \right)$$

• plugging these back into our EOM we get:

$$\frac{d^2 x^i}{dt^2} = -n^{ii} \partial_i \phi + n^{ii} (\partial_i \beta_j - \partial_j \beta_i) v^j$$

• This is our final equation. Vectorially, this represents

$$\frac{d^2 \vec{x}}{dt^2} = -\vec{\nabla} \phi + (\vec{\nabla} \times \vec{\beta}) \times -\vec{v}$$

• Multiply both sides by mass "m" + plug in the definitions of  $\vec{g}$  and  $\vec{H}$  to yield:

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$$m \frac{d^2 \vec{x}}{dt^2} = m \vec{g} + m \vec{v} \times \vec{H} \quad \text{as wanted to show}$$

b. Show that for stationary sources (no  $T_{ur}$  varies with time) the EFE can be written as:



$$\left. \begin{aligned} \bar{\nabla} \cdot \bar{g} &= -4\pi G \rho \\ \bar{\nabla} \times \bar{H} &= -16\pi G \bar{J} \quad \text{where } \bar{J} = \rho \bar{v} \\ \bar{\nabla} \cdot \bar{H} &= 0 \\ \bar{\nabla} \times \bar{g} &= 0 \end{aligned} \right\}$$

where  $\bar{J} = \rho \bar{v}$  is the velocity of fluid flow of the source: Start with the first:

$$\bar{\nabla} \cdot \bar{g} = -\bar{\nabla} \cdot \bar{\nabla} \phi = -\nabla^2 \phi$$

use the Newtonian approximation  $\nabla^2 \phi = 4\pi G \rho$

$$\Rightarrow \boxed{\bar{\nabla} \cdot \bar{g} = -4\pi G \rho \quad \checkmark}$$

Now the second:

$$\cdot \text{use } \square \bar{h}_{\mu\nu} = \nabla^2 \bar{h}_{\mu\nu} = -16\pi G T_{\mu\nu}$$

$$\cdot \text{Assume a dust collection s.t. } T_{\mu\nu} = \rho u_\mu u_\nu$$

$$\rightarrow \nabla^2 \bar{h}_{\mu\nu} = -16\pi G T_{\mu\nu} = -16\pi G \rho u_\mu u_\nu$$

• Narrow  $\nu$  down to spatial indices  $i$ :

$$\rightarrow \nabla^2 \bar{h}_{0i} = -16\pi G \rho v_i, \text{ and now use } h_{0i} = -\beta_i$$



$$\rightarrow \nabla^2 \beta_i = 16\pi G \rho V_i$$

$$\bar{\nabla} \times \bar{H} = \bar{\nabla} \times (\bar{\nabla} \times \bar{B})$$

• Use the identity

$$= \bar{\nabla}(\bar{\nabla} \cdot \bar{B}) - \nabla^2 \bar{B}$$

• And apply the Lorenz / Harmonic gauge condition  
for linearized GR that  $\partial^{\mu} \bar{h}_{\mu\nu} = 0$ :

$$\rightarrow \partial^i \bar{h}_{ir} + \partial^t \bar{h}_{tr} = 0$$

$\downarrow 0$  due to stationary

• Now choose  $\sqrt{-g} = 0$ :

$$\rightarrow \partial^i \bar{h}_{io} = 0 \rightarrow \partial^i \beta_i = 0 \rightarrow \bar{\nabla} \cdot \bar{B} = 0$$

$$\rightarrow \bar{\nabla} \times \bar{H} = -\nabla^2 \bar{B}$$

$$\rightarrow \bar{\nabla} \times \bar{H} = -16\pi G \rho \bar{V} \text{ now insert } \bar{J} = \sqrt{-g} B$$

$$\rightarrow \boxed{\bar{\nabla} \times \bar{H} = -16\pi G \bar{J}} \quad \checkmark$$

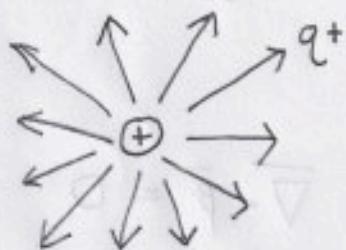
• The last two equations  $\bar{\nabla} \cdot \bar{H} = 0$  +  $\bar{\nabla} \times \bar{g} = 0$   
follow from the vector calculus facts that

$$\operatorname{div}(\operatorname{curl}) = \operatorname{curl}(\operatorname{div}) = 0$$

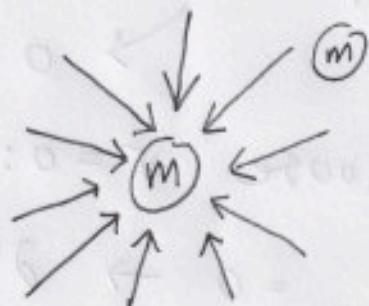
$$\rightarrow \boxed{\bar{\nabla} \cdot \bar{H} = \bar{\nabla} \times \bar{g} = 0}$$

These equations bear a strong resemblance to the Maxwell equations with  $\partial_t \vec{E} = \partial_t \vec{B} = 0$  except for the reversed sign in both equations and extra factor of 4 in the curl equation. Can you explain these differences?

Ans: I think the reversed sign comes down to the fact that 2 masses have gravity act as a sink whereas 2 protons have electromagnetism act as a source:



"Electric Repulsion"



"Gravitational Attraction"

I think the extra factor of 4 in the curl equation comes down to the fact we are working in a higher dimensional space or i.e. space + time are treated more interchangeably so we have "4 space-time" coordinates rather than "3 spatial" coordinates + the "separate" flow of time...

$$\nabla \times (\vec{v} \times \vec{B}) = (\vec{v} \cdot \nabla) \vec{B} - (\vec{B} \cdot \nabla) \vec{v}$$

Carroll 7.1

Show that variation of the Lagrangian:

$$\mathcal{L} = \frac{1}{2} \left[ (\partial_\nu h^{\mu\nu})(\partial_\nu h) - (\partial_\nu h^{\mu\nu})(\partial_\mu h^\nu) + \frac{1}{2} n^{\mu\nu} (\partial_\nu h^{\rho\sigma})(\partial_\nu h_{\rho\sigma}) - \frac{1}{2} n^{\mu\nu} (\partial_\nu h)(\partial_\nu h) \right]$$

Leads to the Einstein Tensor in Linear GR:

$$G_{\mu\nu} = \frac{1}{2} (\partial_\sigma \partial_\nu h^\sigma_\mu + \partial_\sigma \partial_\nu h^\sigma_\nu - \partial_\nu \partial_\nu h - \square h_{\mu\nu} - n_{\mu\nu} \partial_\lambda \partial_\lambda h^{\lambda\mu} + n_{\mu\nu} \square h)$$

We will need to use the following facts:

- $\partial_\nu (\delta g^{\mu\nu}) = \delta (\partial_\nu g^{\mu\nu})$  "variation of partial of metric equals partial of variation of metric"
- $h^{\mu\nu} = n^{\mu\rho} n^{\nu\sigma} h_{\rho\sigma}$  "indices of  $h$  raised and lowered by flat metric  $n$ "
- $\int d^4x \delta(\partial_\nu g^{\mu\nu}) A_\lambda^\bullet = - \int d^4x (\partial_\nu A_\lambda) \delta g^{\mu\nu} + \text{Boundary term}$   
via integration by parts...  $\downarrow$   
 $0 @ \infty$
- Begin by enforcing that: 

$$0 = \delta S = \int \frac{\partial \mathcal{L}}{\partial h^{uv}} \delta h^{uv}$$

and find the variation for each of the 4 terms / summands in  $\mathcal{L}$ :

$$\begin{aligned} \mathcal{L}_1 &= \frac{1}{2} (\partial_u h^{uv}) (\partial_v h) \\ &= \frac{1}{2} (\partial_u h^{uv}) (\partial_v h^{\lambda\beta} h_{\lambda\beta}) \end{aligned}$$

$$\begin{aligned} \rightarrow 0 &= \int \delta \mathcal{L}_1 = \delta S_1 \\ &= \frac{1}{2} \int [(\partial_u h^{uv}) (h^{\lambda\beta} \partial_v \delta h_{\lambda\beta}) \\ &\quad + (\partial_u \delta h^{uv}) (h^{\lambda\beta} \partial_v h_{\lambda\beta})] d^4x \end{aligned}$$

• Apply integration by parts ....

$$\begin{aligned} &= -\frac{1}{2} \int [(\partial_u \partial_v h^{uv}) h^{\lambda\beta} \delta h_{\lambda\beta} \\ &\quad + (\partial_u \partial_v h_{\lambda\beta}) h^{\lambda\beta} \delta h^{uv}] d^4x \end{aligned}$$

$$= -\frac{1}{2} \int [ \partial_u \partial_v h^{uv} n^\lambda \delta h_{\lambda u} n_{v\beta} \delta h^{uv} \\ + \partial_u \partial_v h \delta h^{uv} ] d^4x$$

$$= -\frac{1}{2} \int [ \partial_u \partial_v h_{uv} n^{uu} n^{vv} n^\lambda \delta h_{\lambda u} n_{v\beta} \delta h^{uv} \\ + \partial_u \partial_v h \delta h^{uv} ] d^4x$$

$$= -\frac{1}{2} \int [ \delta_\alpha^u \delta_\beta^v n^\lambda \partial_u \partial_v h_{uv} \delta h^{uv} \\ + (\partial_u \partial_v h) \delta h^{uv} ] d^4x$$

~~Now onto the second terms:~~

$$\rightarrow \delta S_1 = -\frac{1}{2} \int [ \square h_{uv} + \partial_u \partial_v h ] \delta h^{uv} d^4x$$

Now onto the second terms:

$$\delta S_2 = \int \delta L_2 d^4x \quad \text{where}$$

$$L_2 = -\frac{1}{2} (\partial_u h^{\rho\sigma}) (\partial_\rho h^\nu_\sigma) \quad \rightsquigarrow$$

$$= -\frac{1}{2} \int [ \partial_\nu (\delta h^{\rho\sigma}) (n_{\nu\rho} \partial_\rho h^{\mu\nu}) + (\partial_\nu h^{\rho\sigma}) (n_{\nu\rho} \partial_\rho (\delta h^{\mu\nu})) ] d^4x$$

$$= \frac{+1}{2} \int [ n_{\nu\rho} \partial_\nu \partial_\rho h^{\mu\nu} \delta h^{\rho\sigma} + \partial_\nu \partial_\rho h^{\rho\sigma} n_{\nu\rho} \delta h^{\mu\nu} ] d^4x$$

↑  
 Let  $\rho \leftrightarrow \sigma$   
 $\sigma \leftrightarrow \rho$

$$= \frac{+1}{2} \int [ n_{\nu\rho} \partial_\nu \partial_\rho h^{\mu\nu} \delta h^{\rho\sigma} + \partial_\nu \partial_\sigma h^\sigma_\nu \delta h^{\mu\nu} ] d^4x$$

↓  
 Let  $\rho \leftrightarrow \nu$   
 $\sigma \leftrightarrow \mu$

$$= \frac{+1}{2} \int [ \partial_\sigma \partial_\nu n_{\nu\rho} h^{\rho\sigma} \delta h^{\mu\nu} + \partial_\nu \partial_\sigma h^\sigma_\nu \delta h^{\mu\nu} ] d^4x$$

$$= \frac{+1}{2} \int [ \partial_\sigma \partial_\nu h^\sigma_\nu + \partial_\nu \partial_\sigma h^\sigma_\nu ] \delta h^{\mu\nu} d^4x = \delta S_2$$

Now onto the third piece of the overall Lagrangian:

$$L_3 = \frac{1}{4} n^{\mu\nu} (\partial_\nu h^{\rho\sigma}) (\partial_\mu h_{\rho\sigma}) \quad \sim \sim \sim$$

$$\delta S_3 = \int \delta \mathcal{L}_3 \, d^4x$$

$$= \frac{1}{4} \int [ n^{uv} \partial_u (\delta h^{\rho\sigma}) (\partial_v h_{\rho\sigma}) + n^{uv} (\partial_u h^{\rho\sigma}) \partial_v (\delta h_{\rho\sigma}) ] \, d^4x$$

$$= -\frac{1}{4} \int [ n^{uv} (\partial_u \partial_v h_{\rho\sigma}) \delta h^{\rho\sigma} + n^{uv} \partial_u \partial_v h^{\rho\sigma} \delta h_{\rho\sigma} ] \, d^4x$$

flip lower  $\leftrightarrow$  upper

$$= -\frac{1}{2} \int n^{uv} \partial_u \partial_v h_{\rho\sigma} \delta h^{\rho\sigma} \, d^4x$$

$n^{uv} \partial_u \partial_v$

$n^{uv} n^\rho n^\sigma \delta h^{uv}$

$\rightarrow h^{\rho\lambda} n_{\lambda\rho} n_{\sigma\lambda}$

$n_{uv} n^{v\rho} n^{r\lambda} \partial_\rho \partial_\lambda$

$$= -\frac{1}{2} \int n^{uv} n^{r\lambda} n_{\lambda\rho} n_{\sigma\lambda} \partial_u \partial_v h^{\rho\lambda} n^{v\rho} n^\sigma \delta h^{ur} \, d^4x$$

$n^{uv} n^{r\lambda} n_{\lambda\rho} n_{\sigma\lambda} n_{uv} n^\rho n^\sigma$

$$= \delta_{\lambda}^{\nu} n^{\sigma \lambda} n_{\rho \sigma} n_{\nu}^{\rho} n_{\sigma}^{\sigma}$$
$$\downarrow \delta_{\sigma \nu}$$

$$\downarrow \delta^{\lambda \sigma}$$

$$= \delta_{\lambda}^{\nu} \delta^{\lambda \sigma} \delta_{\sigma \nu} = \delta_{\lambda}^{\nu} \delta_{\nu}^{\lambda} = \delta_{\lambda}^{\lambda} \rightarrow \text{"Identity Matrix"}$$

• So overall ...

$$\delta S_3 = -\frac{1}{2} \int n_{\nu r} \partial_{\rho} \partial_{\lambda} h^{\rho \lambda} \delta h^{r\nu} d^4x$$

• Now the forth + final piece of the Lagrangian:

$$L_4 = -\frac{1}{4} n^{\nu r} (\partial_{\nu} h) (\partial_r h)$$

$$\delta S_4 = \int \delta L_4 d^4x$$

$$= -\frac{1}{4} \int [ n^{\nu r} \partial_{\nu} (\delta h_{\alpha \beta} n^{\alpha \beta}) (\partial_r h_{\gamma w} n^{\gamma w}) + n^{\nu r} (\partial_{\nu} h_{\alpha \beta} n^{\alpha \beta}) \partial_r (\delta h_{\gamma w} n^{\gamma w}) ] d^4x$$

$$= +\frac{1}{4} \int [n^{uv} n^{rw} n^{\lambda\beta} (\partial_u \partial_r h_{\lambda\beta}) \delta h_{\lambda\beta} \\ + n^{uv} n^{rw} n^{\lambda\beta} (\partial_u \partial_r h_{\lambda\beta}) \delta h_{rw}] d^4x$$

h

② flip lower to upper  
+ relabel dummies to  $uv$

$$= +\frac{1}{4} \int 2 n^{uv} \partial_u \partial_v h n_{uv} \delta h^{uv} d^4x$$

$$= +\frac{1}{2} \int n_{uv} \square h \delta h^{uv} d^4x = \delta S_4$$

Now we get:

$$\delta S_{tot} = \delta S_1 + \delta S_2 + \delta S_3 + \delta S_4 = 0$$

$$\rightarrow \frac{1}{2} (-\square h_{uv} - \partial_u \partial_v h + \partial_\sigma \partial_v h^\sigma_u + \partial_\sigma \partial_u h^\sigma_v \\ - n_{uv} \partial_\rho \partial_\lambda h^{\rho\lambda} + n_{uv} \square h) = 0 \quad \star$$

- Equation  $\star$  exactly matches the linearized Einstein tensor given by Carroll + we have since found the EFE in Linear GR with no sources (i.e.  $T_{\mu\nu} \rightarrow 0$ ):

$$\rightarrow G_{\mu\nu} = 0 \quad \underline{\text{Q.E.D.}}$$

### Carroll 7.4

- Show that the Harmonic gauge  $\square x^\nu = 0$  is equivalent to the Lorentz gauge  $\partial_\nu h^{\mu\nu} = 0$ :
- Let's first simplify  $\square x^\nu = 0$ :
  - In flat-spacetime,  $\square = g^{\alpha\beta} \partial_\alpha \partial_\beta$ ; however, more generally,  $\square = g^{\alpha\beta} \nabla_\alpha \nabla_\beta$ . We have to use this more general form in our derivation...
  - Also note that  $x^\nu$  is not a vector, but just a single coordinate component so the first  $\nabla_\beta$  reduces to  $\nabla_\beta x^\nu = \partial_\beta x^\nu = \delta_\beta^\nu$

$$\rightarrow \square x^\nu = 0$$

$$\rightarrow g^{\alpha\beta} \nabla_\alpha (\delta_\beta^\nu) = 0$$

$$\rightarrow g^{\alpha\beta} \left( \underbrace{\partial_\alpha \delta_\beta^\nu}_{\emptyset} + \Gamma_{\alpha\beta}^\nu \underbrace{\delta_\nu^\beta}_{1} \right) = 0$$

$$\rightarrow g^{\alpha\beta} \Gamma_{\alpha\beta}^\nu = 0 \quad \star$$

We will need to use this relationship later... It is an equivalent form of  $\square x^\nu = 0$

- Now use the fact that we have metric compatibility + take the divergence of the metric:

$$\nabla_\nu g^{\nu r} = 0$$

$$\rightarrow \partial_\nu g^{\nu r} + \underbrace{\Gamma_{\nu\lambda}^\nu g^{\lambda r}}_{\emptyset \text{ by } \star} + \Gamma_{\nu r}^\nu g^{\lambda\lambda} = 0$$

$$\rightarrow \partial_\nu g^{\nu r} + \underbrace{\Gamma_{\nu\lambda}^\nu g^{\lambda r}}_{\text{relabel dummies } N \rightarrow r} = 0$$

$$\rightarrow \partial_\nu g^{\nu r} + \underbrace{\Gamma_{\nu r}^\nu g^{\lambda\lambda}}_{\emptyset \text{ by } \star} = 0$$

$$\rightarrow \partial_\nu g^{\nu r} = 0 \quad *$$

- So we have shown that given metric compatibility + the Harmonic gauge  $\square x^\mu = 0$  not only does  $\nabla_\nu g^{\mu\nu} = 0$  but also  $\partial_\nu g^{\mu\nu} = 0$
- Now we will express  $g^{\mu\nu}$  in terms of  $\bar{h}^{\mu\nu}$  to recover the Lorentz gauge condition:
- We know from Carroll's text that  $\bar{h}_{\mu\nu}$  is defined s.t. its trace  $n^{\mu\nu} \bar{h}_{\mu\nu}$  equals the negative trace "h" of  $h_{\mu\nu}$ . We will find  $\bar{h}^{\mu\nu}$  by setting its trace to  $-h$  as well:

$$n_{\mu\nu} \bar{h}^{\mu\nu} = \bar{h} = -n_{\mu\nu} h^{\mu\nu} = -h$$

$$\rightarrow \bar{h}^{\mu\nu} = h^{\mu\nu} - \frac{1}{2} n^{\mu\nu} h$$

- Now use the facts that:

$$\left. \begin{aligned} g_{\mu\nu} &= n_{\mu\nu} + h_{\mu\nu} \\ g^{\mu\nu} &= n^{\mu\nu} - h^{\mu\nu} \end{aligned} \right\}$$

$$\rightarrow \bar{h}^{\mu\nu} = n^{\mu\nu} - g^{\mu\nu} - \frac{1}{2} n^{\mu\nu} n_{\alpha\beta} (n^{\alpha\beta} - g^{\alpha\beta})$$

$$\rightarrow \bar{h}^{nr} = n^{nr} - g^{nr} - 2n^{nr} + \frac{1}{2} n^{nr} n_{\alpha\beta} g^{\alpha\beta}$$

↑  
change dummy  
to  $N^r$

$$\rightarrow \bar{h}^{nr} = -g^{nr} - n^{nr} + 2g^{nr}$$

$$\rightarrow \bar{h}^{nr} = g^{nr} - n^{nr}$$

- Now take partial w.r.t.  $N^r$ :

$$\partial_N \bar{h}^{nr} = \partial_N g^{nr} - \partial_N n^{nr} \rightarrow 0$$

$$\rightarrow \partial_N \bar{h}^{nr} = \partial_N g^{nr} = 0 \text{ by relation } (*)$$

- so in the end we recover  $\boxed{\partial_N \bar{h}^{nr} = 0}$

as we wanted to show  $\checkmark$  Q.E.D.

Carroll Chapter 7, Part 3

- Fermat's principle states that a light ray moves along a path of least time. For a medium with refractive index  $n(\vec{x})$  this is equivalent to extremizing the time:



$$t = \int n(\vec{x}) [\delta_{ij} dx^i dx^j]^{1/2} \text{ along the path.}$$

Show that Fermat's principle with refractive index  $n = 1 - 2\phi$  leads to the correct EOM for a photon in a spacetime perturbed by a Newtonian potential:

A photon is lightlike/null which means its invariant interval obeys the following rule:

$$0 = ds^2 = g_{\mu\nu} dx^\mu dx^\nu = g_{\mu\nu} \frac{dx^\mu}{dt} \cdot \frac{dx^\nu}{dt} \quad (*)$$

Break this up explicitly:

$$0 = g_{tt} \left( \frac{dt}{dt} \right)^2 + g_{ij} \frac{dx^i}{dt} \cdot \frac{dx^j}{dt}$$

$$\rightarrow -g_{tt} = (n_{ij} - 2\phi \delta_{ij}) \left( \frac{dx^i}{dt} \cdot \frac{dx^j}{dt} \right)$$

$$\rightarrow -g_{tt} = (1 - 2\phi) \delta_{ij} \frac{dx^i}{dt} \cdot \frac{dx^j}{dt}$$

$$\rightarrow -g_{tt} = (1 - 2\phi) \frac{ds^2}{dt^2}$$

$$\rightarrow -(-1 - 2\phi) = (1 - 2\phi) \left( \frac{ds}{dt} \right)^2$$

$$\rightarrow \frac{1+2\phi}{1-2\phi} = \left(\frac{ds}{dt}\right)^2$$

$$\rightarrow \left(\frac{ds}{dt}\right)^2 \propto (1+2\phi)^2 \text{ since } \phi \ll 1 \Rightarrow \phi^2 \approx 0$$

$$\rightarrow (1+2\phi) = ds/dt$$

$$\rightarrow \int \frac{ds}{1+2\phi} = \int dt$$

$$\rightarrow \int (1-2\phi) ds = t$$

$$\rightarrow \boxed{\int n(\vec{x}) [\delta_{ij} dx^i dx^j]^{1/2} = t} \quad \checkmark \quad \star$$

• So  $\oplus$  and  $\star$  are logically equivalent. Starting from the EOM of a photon we can derive the Fermat integral or we could equivalently work our way backward as well...  $\checkmark$